age (250mV at 500mA).

continuous current.

battery detector.

space than discrete solutions.

Notebook and Sub-Notebook Computers Wake-On LAN

2 to 4 Li+ Cells Battery-Powered Devices

# **MAXM**

# *High-Efficiency, Triple-Output, Keep-Alive Power Supply for Notebook Computers*

### *General Description*

The MAX1534 is a high-efficiency, triple-output power supply for keep-alive (always on) voltage rails. The 500mA buck regulator with an internal current-limited 0.5Ω PMOS steps down the battery or wall adapter supply rail to a fixed 5V or an adjustable output voltage. Two integrated low-voltage linear regulators follow this output and provide two independent preset output voltages of 3.3V and 1.8V, or adjustable output voltages. The buck regulator utilizes a peak current-limit, pulsefrequency modulation (PFM) architecture for highest light-load efficiency to conserve battery life. High switching frequencies (up to 200kHz) allow the use of tiny surface-mount inductors and output capacitors. Operation to 100% duty cycle minimizes dropout volt-

The low-dropout linear regulators use an internal P-channel metal-oxide (PMOS) pass transistor to minimize supply current and deliver up to 160mA each of

The MAX1534 includes a power-OK (POK) signal that indicates all outputs are in regulation. The 4% accurate threshold of the SHDN input permits its use as a low-

The MAX1534 is available in a small 16-pin thin QFN  $(4mm \times 4mm)$  package, occupying 33% less board

*Applications*

Hand-Held Devices Keep-Alive Supplies Standby Supplies

### *Features*

- ♦ **One Switching and Two Linear Regulators**
- ♦ **Switching Regulator +4.5V to +24V Input Voltage Range Over 95% Efficiency Up to 500mA Output Current Up to 200kHz Switching Frequency Fixed 5V or Adjustable Output Voltage Internal 0.5**Ω **PMOS Switch 100% Maximum Duty Cycle for Low-Dropout Operation**
- ♦ **Two Low-Dropout Linear Regulators Up to 160mA Output Current (Each) 3.3V/Adj Output Voltage for OUT1 1.8V/Adj Output Voltage for OUT2**
- ♦ **±1.5% Accurate Output Voltage**
- ♦ **±4% Accurate Shutdown for Low Battery Detection**
- ♦ **Thermal Shutdown Protection**
- ♦ **POK Output**
- ♦ **1mW Typical Standby Power**

### *Ordering Information*



*Pin Configuration appears at end of data sheet.*

# *Typical Operating Circuit*



### **MAXIM**

**\_** *Maxim Integrated Products* **1**

*For pricing, delivery, and ordering information, please contact Maxim/Dallas Direct! at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.*

### **ABSOLUTE MAXIMUM RATINGS**





*Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.*

### **ELECTRICAL CHARACTERISTICS**

(Circuit of Figure 1, VIN = 12V, ILIM = GND, PRESET = GND, **TA = 0°C to +85°C**, unless otherwise noted. Typical values are at TA =  $+25^{\circ}$ C.)



**MAXIM** 

## **ELECTRICAL CHARACTERISTICS (continued)**

(Circuit of Figure 1, VIN = 12V, ILIM = GND, PRESET = GND, **TA = 0°C to +85°C**, unless otherwise noted. Typical values are at TA =  $+25^{\circ}$ C.)



# **ELECTRICAL CHARACTERISTICS**

(Circuit of Figure 1, VIN = 12V, ILIM = GND, PRESET = GND, **TA = -40°C to +85°C**, unless otherwise noted.) (Note 4)



**MAXIM** 

### **ELECTRICAL CHARACTERISTICS (continued)**

(Circuit of Figure 1, VIN = 12V, ILIM = GND, PRESET = GND, **TA = -40°C to +85°C**, unless otherwise noted.) (Note 4)



**Note 1:** The output voltage at light loads has a DC regulation level higher than the error comparator threshold by half the ripple voltage.

**Note 2:** The dropout voltage is defined as V<sub>LDOIN</sub> - V<sub>OUT\_</sub> when V<sub>LDOIN</sub> = V<sub>OUT\_(NOM)</sub>. Specification only applies when V<sub>OUT</sub> ≥ 2.5V.

**Note 3:** OUT1, OUT2 DC set point, FB3 set point at the DC trip threshold of buck regulator.

**Note 4:** Specifications to -40°C are guaranteed by design, not production tested.

(Circuit of Figure 1,  $V_{IN}$  = +12V,  $\overline{PRESET}$  = GND,  $T_A$  = +25°C, unless otherwise noted.)



*Typical Operating Characteristics*

*MAX1534* **MAX1534** 

### *Typical Operating Characteristics (continued)*

(Circuit of Figure 1,  $V_{IN}$  = +12V, PRESET = GND,  $T_A$  = +25°C, unless otherwise noted.)

**MAX1534** *MAX1534*



### *Typical Operating Characteristics (continued)*

(Circuit of Figure 1,  $V_{IN} = +12V$ , PRESET = GND,  $T_A = +25^{\circ}C$ , unless otherwise noted.)







 $V_{1N} = 12V$ ,  $R_{01JT1} = 33Ω$ ,  $R_{01JT2} = 18Ω$ ,  $R_{01JT3} = 50Ω$ 





20µs/div  $V_{LDOIN} = 5V$ ,  $I_{OUT1} = 10$ ma TO 150ma



**MAXIM** 

### *Pin Description*



# *Detailed Description*

The MAX1534 regulator provides efficient light-load power conversion for notebook computers or hand-held devices that require keep-alive power or standby power. The main step-down buck regulator uses a unique peak current-limited control scheme, providing high efficiency at light loads over a wide load range. Operation up to 100% duty cycle allows the lowest possible dropout voltage, increasing the usable supply voltage range. Under no load, the MAX1534 consumes only 1mW, and in shutdown mode, it draws only 3.5µA. The internal 24V switching MOSFET, internal current sensing, and a high-switching frequency minimize PC board space and component costs.

The MAX1534 includes two low-noise, low-dropout, low-quiescent-current linear regulators. The linear regulators are available with preset output voltages of 3.3V and 1.8V. Each linear regulator can supply loads up to 160mA.



**MAX1534** *MAX1534*



*Figure 1. MAX1534 Typical Application Circuit*

The MAX1534 PFM step-down topology consumes less power than the traditional linear regulator solution when converting from a high-input voltage source.

#### *Buck Converter*

#### *Current-Limited Control Architecture*

The MAX1534's buck converter uses a proprietary current-limited control scheme with operation to 100% duty cycle. This DC-to-DC converter pulses as needed to maintain regulation, resulting in a variable switching frequency that increases with the load. This eliminates the high supply currents associated with conventional constant-frequency pulse-width-modulation (PWM) controllers that switch the MOSFET unnecessarily.

When the output voltage is too low, the error comparator sets a flip-flop, which turns on the internal P-channel MOSFET and begins a switching cycle (Figure 2). As shown in Figure 3, the inductor current ramps up linearly, storing energy in a magnetic field while charging the output capacitor and servicing the load. The MOSFET turns off when the peak current limit is reached, or when the maximum on-time of 10µs is exceeded and the output voltage is in regulation. If the output is out of regulation and the peak current is never reached, the MOSFET remains on, allowing a duty cycle up to 100%. This feature ensures the lowest possible dropout voltage. Once the MOSFET turns off, the flip-flop resets, the inductor

current is pulled through D1, and the current through the inductor ramps back down, transferring the stored energy to the output capacitor and load. The MOSFET remains off until the 0.42µs minimum off-time expires, and the output voltage drops out of regulation.

#### *Current Limit (ILIM)*

*MAX1534*

**MAX1534** 

The MAX1534's buck converter has an adjustable peak current limit. Configure this peak current limit by connecting ILIM as shown in Table 3. Choose a current limit that realistically reflects the maximum load current. The maximum output current is half the peak current limit. Although choosing a lower current limit allows using an inductor with a lower current rating, it requires a higher inductance (see *Inductor Selection*) and does little to reduce inductor package size.

ILIM can be dynamically switched to achieve the highest efficiency over the load range. (See Buck Efficiency vs. Load Current (Circuit 1) in the *Typical Operating Characteristics*.

#### *Linear Regulators*

#### *Internal P-Channel Pass Transistor*

The MAX1534 features two 1.5Ω P-channel MOSFET pass transistors. A P-channel MOSFET provides several advantages over similar designs using PNP pass transistors, including longer battery life. It requires no



**\_ 9**





### **Table 2. Component Suppliers**



base drive, which reduces quiescent current significantly. PNP-based regulators waste considerable current in dropout when the pass transistor saturates, and they also use high base-drive currents under large

### **Table 3. Current-Limit Configuration**



loads. The MAX1534 does not suffer from these problems. While a PNP-based regulator has dropout voltage that is independent of the load, a P-channel MOSFET's dropout voltage is proportional to load current, providing for low dropout voltage at heavy loads and extremely low dropout voltage at lighter loads.

#### *Current Limit*

The MAX1534 contain two independent current limiters, one for each linear regulator, which monitor and control the pass transistor's gate voltage, limiting the guaranteed maximum output current to 160mA minimum. The output can be shorted to ground for an indefinite time without damaging the part.

#### *Low-Noise Operation*

An external 0.01µF bypass capacitor at BP, in conjunction with an internal resistor, creates a lowpass filter, reducing the LDO output voltage noise.

#### *Shutdown (*SHDN*)*

The MAX1534's accurate SHDN input can be used as a low-battery voltage detector. Drive SHDN above the 1V input rising-edge trip level to start up the MAX1534. The 100mV SHDN input hysteresis prevents the MAX1534 from oscillating between startup and shutdown. Drive SHDN low to shut down the MAX1534's buck converter and linear regulators. When in shut-





*Figure 2. MAX1534 Functional Block Diagram*

down, the supply current drops to 3.5µA, maximizing battery life. The internal P-channel MOSFET in the buck converter and linear regulators turn off to isolate each input from its output. The output capacitance and load current determine the rate at which the output voltage decays. For automatic shutdown and startup, connect SHDN to IN. Connect SHDN to IN through a resistive voltage-divider to implement a programmable undervoltage lockout. Do not leave SHDN floating.

#### *Power-OK (POK)*

The open-drain POK output is useful as a simple error flag, as well as a delayed reset output. POK sinks current when any of the three regulated output voltages is 11% below its regulation point. Connect POK to OUT\_ through a high-value resistor for a simple error flag indi-

**MAXIM** 

cator. Connect a capacitor from POK to GND to produce a delayed POK signal (delay set by the RC time constant). POK is low in shutdown and is high impedance when all three outputs are in regulation.

#### *Thermal-Overload Protection*

Thermal-overload protection limits total power dissipation in the MAX1534. When the junction temperature exceeds  $T_{J}$  = +160 $\degree$ C, a thermal sensor turns off the pass transistor, allowing the IC to cool. The thermal sensor turns the IC on again after the IC's junction temperature cools by 15°C, resulting in a pulsed output during continuous thermal-overload conditions.

Thermal-overload protection is designed to protect the MAX1534 in the event of fault conditions. For continu-

junction temperature rating of  $T_{\text{J}} = +150^{\circ}$ C.

**Propose the absolute maximum**<br> **Conserved the absolute maximum**<br> **Conserved the absolute maximum**<br>
The MAX1534's maximum power dissipation depends<br>
on the thermal resistance of the case and circuit board,<br>
the temperatur *Operating Region and Power Dissipation* The MAX1534's maximum power dissipation depends on the thermal resistance of the case and circuit board, the temperature difference between the die junction and ambient air, and the rate of air flow. The power dissipated in the device is the sum of the buck MOSFET switching and conduction losses and the linear regulators' conduction losses. The maximum power dissipation is:

$$
P_{MAX} = (T_J - T_A) / (\theta_{JB} + \theta_{BA})
$$

where T<sub>J</sub> - T<sub>A</sub> is the temperature difference between the MAX1534 die junction and the surrounding air, θ JB (or  $\theta$ JC) is the thermal resistance of the package, and  $\theta_{BA}$  is the thermal resistance through the printed circuit board, copper traces, and other materials to the surrounding air. The exposed backside pad of the MAX1534 provides a low thermal impedance to channel heat out of the package. Connect the exposed backside pad to ground using a large pad or ground plane.

#### *Preset and Adjustable Output Voltages (*PRESET*)*

The MAX1534 features dual mode operation; it operates in either a preset voltage mode (see Table 4) or an adjustable mode. In preset voltage mode, internal trimmed feedback resistors set the MAX1534 outputs to 3.3V for  $V_{\text{OUT1}}$ , 1.8V for  $V_{\text{OUT2}}$ , and 5.0V for FB3 (buck regulator). Select this mode by connecting PRESET to ground. Connect PRESET to IN to operate the MAX1534 in the adjustable mode. Select an output voltage using two external resistors connected as a voltage-divider to FB\_ (Figure 4). The output voltage is set by the following equation:

$$
V_{OUT} = V_{FB} \left( 1 + \frac{R_{TOP}}{R_{BOT}} \right)
$$

where  $VFB = 1.0V$ , VOUT1 and VOUT2 can range from 1.0V to VLDOIN, and VOUT3 can range from 1.0V to VIN. To simplify resistor selection:

$$
R_{\text{TOP}_{-}} = R_{\text{BOT}_{-}} \left( \frac{V_{\text{OUT}_{-}}}{V_{\text{FB}_{-}}} - 1 \right)
$$

Choose R<sub>BOT</sub> = 100k $\Omega$  to optimize power consumption, accuracy, and high-frequency power-supply rejection. The total current through the external resistive feedback and load resistors should not be less than 10µA. Since the V<sub>FB</sub> tolerance is typically less than

### **Table 4.** PRESET **Setting**



±15mV, the output can be set using fixed resistors instead of trim pots.

### *Design Procedure*

#### *Buck Converter*

#### *Inductor Selection*

When selecting the inductor, consider these four parameters: inductance value, saturation rating, series resistance, and size. The MAX1534 operates with a wide range of inductance values. For most applications, values between 10µH and 50µH work best with the controller's high switching frequency. Larger inductor values reduce the switching frequency and thereby improve efficiency and EMI. The trade-off for improved efficiency is a higher output ripple and slower transient response. On the other hand, low-value inductors respond faster to transients, improve output ripple, offer smaller physical size, and minimize cost. If the inductor value is too small, the peak inductor current exceeds the current limit due to current-sense comparator propagation delay, potentially exceeding the inductor's current rating. Calculate the minimum inductance value as follows:

$$
L_{(MIN)} = \frac{(V_{IN(MAX)} - V_{OUT3}) \times t_{ON(MIN)}}{I_{LX(PEAK)}}
$$

where  $\text{ton}(\text{MIN}) = 0.5\mu\text{s}$ .

The inductor's saturation current rating must be greater than the peak switch current limit, plus the overshoot due to the 150ns current-sense comparator propagation delay. Saturation occurs when the inductor's magnetic flux density reaches the maximum level the core can support and the inductance starts to fall. Choose an inductor with a saturation rating greater than IPEAK in the following equation:

 $IPEAK = ILX(PEAK) + (V_{IN} - V_{OUT3}) \times 150$ ns / L

Inductor series resistance affects both efficiency and dropout voltage (see the *Buck Dropout Performance* section).

High series resistance limits the maximum current available at lower input voltages, and increases the dropout





*Figure 3. Normal Buck Operation*

voltage. For optimum performance, select an inductor with the lowest possible DC resistance that fits in the allotted dimensions. Some recommended component manufacturers are listed in Table 2.

#### *Maximum Buck Output Current*

The MAX1534's buck converter's maximum output current is limited by the peak inductor current. For the typical application, the maximum output current is approximately:

 $I$ OUT3(MAX) =  $1/2$   $I$ LX (PEAK)(MIN)

For low-input voltages, the maximum on-time can be reached and the load current is limited by:

 $I_{OUT3} = 1/2$  (V<sub>IN</sub> - V<sub>OUT3</sub>)  $\times$  10µs / L

Note that any current provided by the linear regulators comes from the buck regulator and subtracts from the maximum current that the buck provides for other loads.

#### *Buck Output Capacitor Selection*

Choose the output capacitor to service the maximum load current with acceptable voltage ripple. The output ripple has two components: variations in the charge stored in the output capacitor with each LX pulse, and the voltage drop across the capacitor's equivalent series resistance (ESR) caused by the current into and out of the capacitor:

 $V$ RIPPLE  $\cong$   $V$ RIPPLE(ESR) +  $V$ RIPPLE(C)

The output voltage ripple as a consequence of the ESR and output capacitance is:

$$
V_{RIPPLE(ESR)} = ESR \times IPEAK
$$



*Figure 4. Adjustable Output Voltages*

$$
V_{RIPPLE(C)} = \frac{L \times (I_{PEAK} - I_{OUT3})^2}{2C_{OUT3} \times V_{OUT3}} \left(\frac{V_{IN}}{V_{IN} - V_{OUT3}}\right)
$$

where IPEAK is the peak inductor current (see *Inductor Selection*). The worst-case ripple occurs at no load. These equations are suitable for initial capacitor selection, but final values should be set by testing a prototype or evaluation circuit. As a general rule, a smaller amount of charge delivered in each pulse results in less output ripple. Since the amount of charge delivered in each oscillator pulse is determined by the inductor value and input voltage, the voltage ripple increases with larger inductance, and as the input voltage decreases. See Table 1 for recommended capacitor values and Table 2 for recommended component manufacturers.

#### *Buck Input Capacitor Selection*

The input filter capacitor reduces peak currents drawn from the power source and reduces noise and voltage ripple on the input caused by the circuit's switching. The input capacitor must meet the ripple-current requirement (IRMS) imposed by the switching current defined by the following equation:

$$
I_{RMS} = \frac{I_{OUT3} \times V_{OUT3}}{V_{IN}} \sqrt{\left(\frac{4}{3}\right)} \times \frac{V_{IN}}{V_{OUT3}} - 1
$$

For most applications, nontantalum chemistries (ceramic, aluminum, polymer, or OSCON) are preferred due to their robustness to high inrush currents typical of systems with low-impedance battery inputs. Choose an



ture rise at the RMS input current for optimal circuit longevity.

#### *Diode Selection*

*MAX1534*input capacitor that exhibits less than +10°C tempera-The current in the external diode (D1 in Figure 1) changes abruptly from zero to its peak value each time the LX switch turns off. To avoid excessive losses, the diode must have a fast turn-on time and a low forward voltage. Make sure that the diode's peak current rating exceeds the peak current set by the current limit, and that its breakdown voltage exceeds V<sub>IN</sub>. Use Schottky diodes when possible.

#### *Linear Regulators Capacitor Selection and LDO Stability*

Use a 2.2µF capacitor on the MAX1534 LDOIN pin and a 2.2µF capacitor on the outputs. Larger input capacitor values and lower ESRs provide better supply-noise rejection and line-transient response. To reduce noise, improve load transients, and for loads up to 160mA, use larger output capacitors (up to 10µF). For stable operation over the full temperature range and with load currents up to 80mA, use 2.2µF. Note that some ceramic dielectrics exhibit large capacitance and ESR variation with temperature. With dielectrics such as Z5U and Y5V, it may be necessary to use 4.7µF or more to ensure stability at temperatures below -10°C. With X7R or X5R dielectrics, 2.2µF is sufficient at all operating temperatures. These regulators are optimized for ceramic capacitors, and tantalum capacitors are not recommended.

Use a 0.01µF bypass capacitor at BP for low output voltage noise. Increasing the capacitance slightly decreases the output noise, but increases the startup time.

### *Applications Information*

#### *Buck Dropout Performance*

A step-down converter's minimum input-to-output voltage differential (dropout voltage) determines the lowest usable supply voltage. In battery-powered systems, this limits the useful end-of-life battery voltage. To maximize battery life, the MAX1534 operates with duty cycles up to 100%, which minimizes the dropout voltage and eliminates switching losses while in dropout. When the supply voltage approaches the output voltage, the P-channel MOSFET remains on continuously to supply the load.

For a step-down converter with 100% duty cycle, dropout depends on the MOSFET drain-to-source onresistance and inductor series resistance; therefore, it is proportional to the load current:

 $VDPOUT(BUCH) = IOUT3 \times (R_LX + RINDUCTOR)$ 

#### *LDO PSRR*

The MAX1534's linear regulators are designed to deliver low dropout voltages and low quiescent currents in battery-powered systems. Power-supply rejection is 55dB at low frequencies and rolls off above 20kHz. (See the LDO PSRR vs. Frequency graph in the *Typical Operating Characteristics*.)

To improve supply-noise rejection and transient response, increase the values of the input and output bypass capacitors or use passive filtering techniques.

#### *LDO Dropout Voltage*

A linear regulator's minimum input-output voltage differential (or dropout voltage) determines the lowest usable supply voltage. Because the MAX1534 uses a P-channel MOSFET pass transistor, its dropout voltage is a function of drain-to-source on-resistance  $(RDS(ON))$ multiplied by the load current (see LDO Dropout Voltage vs. Load Current in the *Typical Operating Characteristics*).

#### *PC Board Layout Guidelines*

High switching frequencies and large peak currents make PC board layout an important part of the design. Poor layout introduces switching noise into the feedback path, resulting in jitter, instability, or degraded performance. High current traces, highlighted in the *Typical Application Circuit* (Figure 1), should be as short and wide as possible. Additionally, the current loops formed by the power components (C<sub>IN</sub>, C<sub>OUT3</sub>, L<sub>1</sub>, and D<sub>1</sub>) should be as short as possible to avoid radiated noise. Connect the ground pins of these power components at a common node in a star-ground configuration. Separate the noisy traces, such as the LX node, from the feedback network with grounded copper. Furthermore, keep the extra copper on the board and integrate it into a pseudoground plane. When using external feedback, place the resistors as close to the feedback pin as possible to minimize noise coupling.

## **Pin Configuration Chip Information**



TRANSISTOR COUNT: 1512 PROCESS: BiCMOS

### *Package Information*

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to **[www.maxim-ic.com/packages](http://www.maxim-ic.com/packages)**.)





*Maxim cannot assume responsibility for use of any circuitry other than circuitry entirely embodied in a Maxim product. No circuit patent licenses are implied. Maxim reserves the right to change the circuitry and specifications without notice at any time.*

#### **16** *\_Maxim Integrated Products, 120 San Gabriel Drive, Sunnyvale, CA 94086 408-737-7600*

© 2002 Maxim Integrated Products Printed USA MAXIM is a registered trademark of Maxim Integrated Products.